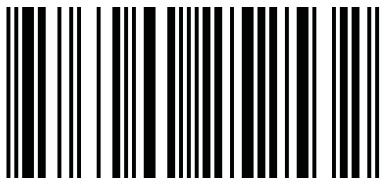
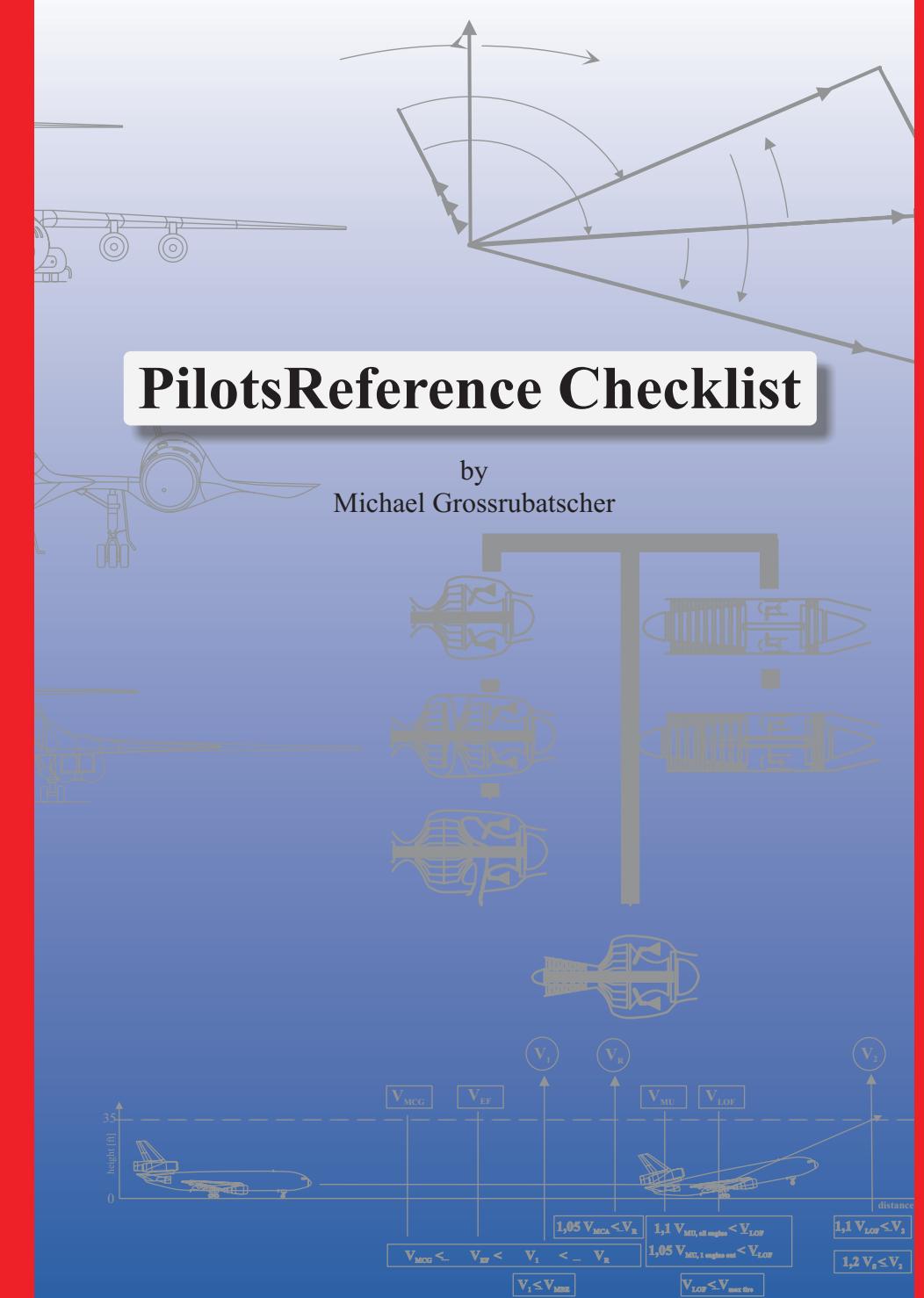


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by Michael Grossrubatscher
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Released: 30.06.2008
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I. Navigation

λ = longitude (long), ρ = latitude (lat)



1. Distance between meridians

$$\alpha = \Delta\lambda \cdot \cos \rho \cdot 60$$

2. Meridian convergence

$$mc = \Delta\lambda \cdot \sin \rho_m \quad (\rho_m = \text{middle latitude})$$

3. Dimensions

- equator & meridians:
- on equator/meridian:
- earth's diameter:
- rotation:

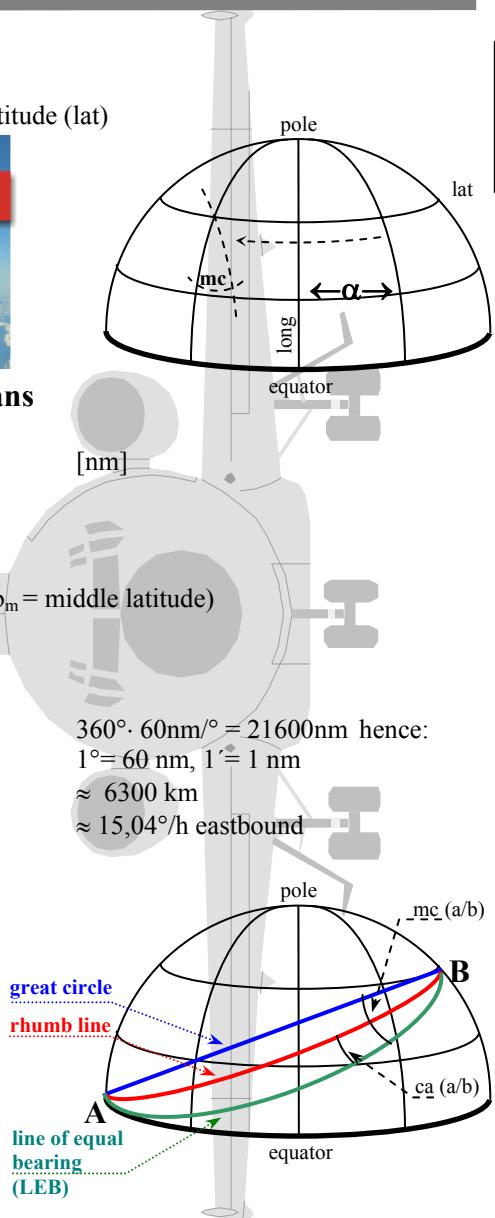
360° · 60nm/° = 21600nm hence:
 1° = 60 nm, 1' = 1 nm
 ≈ 6300 km
 ≈ 15,04°/h eastbound

4. Conversion angle

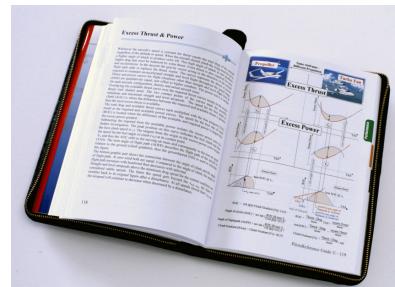
$$ca = \frac{1}{2} \cdot mc$$

- angle: great circle/rhumb line
- angle: rhumb line /LEB

great circle	shortest connection	VOR
rhumb line	Constant course	
LEB	constant bearing	ADF only

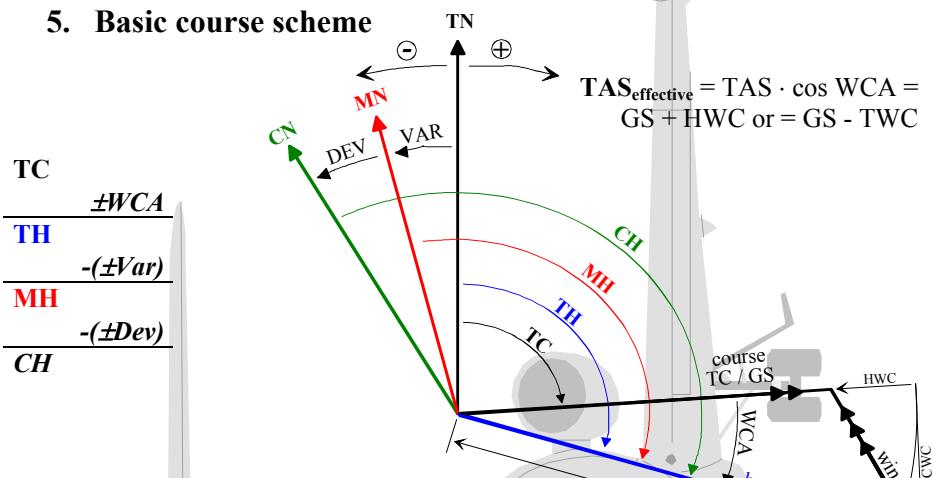


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5. Basic course scheme



6. Advanced course scheme

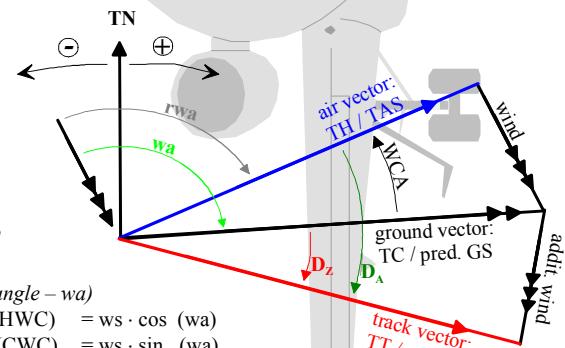
- wa = wind angle
- rwa = resultant wa
- addit. wind = additional wind
- D_A = drift angle
- D_Z = addit. Drift

	from	to
WCA	course	heading
D_A	heading	track
D_Z	course	track

7. Wind components

(Wind speed – ws; Wind angle – wa)

- Headwind component (HWC) = $ws \cdot \cos (wa)$
- Crosswind component (CWC) = $ws \cdot \sin (wa)$



8. 1:60 Rule

(Lateral deviation from desired track - VOR vs. GPS)

$$\text{Lateral deviation [nm]} = \frac{\text{Distance to fix} \cdot \text{lateral deviation } [{}^{\circ}]}{60}$$

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9. Grid nav course scheme

- G_{cvg} = grid convergence
- griv = gravitation
- Var = variation
- GC = grid course

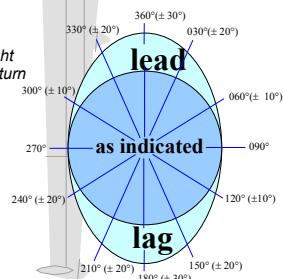
$$\Rightarrow G_{cvg} = \Delta\lambda \cdot cc$$

- $\Delta\lambda$: (LM: local meridian, ref. M: reference meridian)
 - LM west of ref. M → - $\Delta\lambda$ (negative prefixed)
 - LM east ref. M → + $\Delta\lambda$ (positive prefixed)
- constant of cone (cc)
 - (always ± 1 for stereographic projection)
 - cc = +1 in northern hemisphere
 - cc = -1 in southern hemisphere

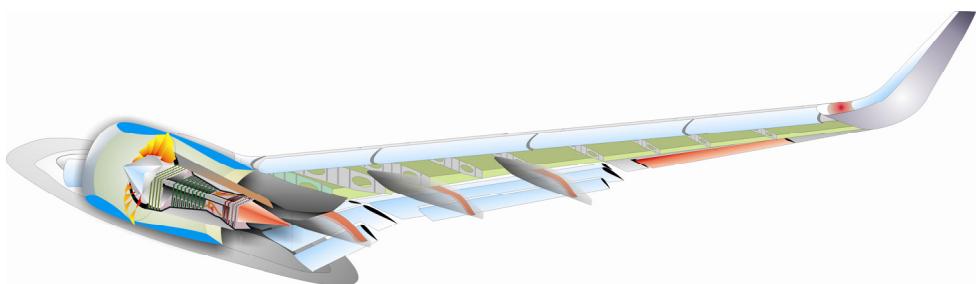
10. Magnetic compass

- 6mT: compass erratic line
- Acceleration error:
Acceleration north, deceleration south on easterly/westerly headings
- Turn error (magnetic compass indication):

- inner circle shows compass indication in straight & level flight
- outer circle shows compass indication within standard rate turn
- compass leads in northern half in the direction of the turn
- compass lags in southern half in the direction of the turn
- see lead/lag: values depicted in brackets

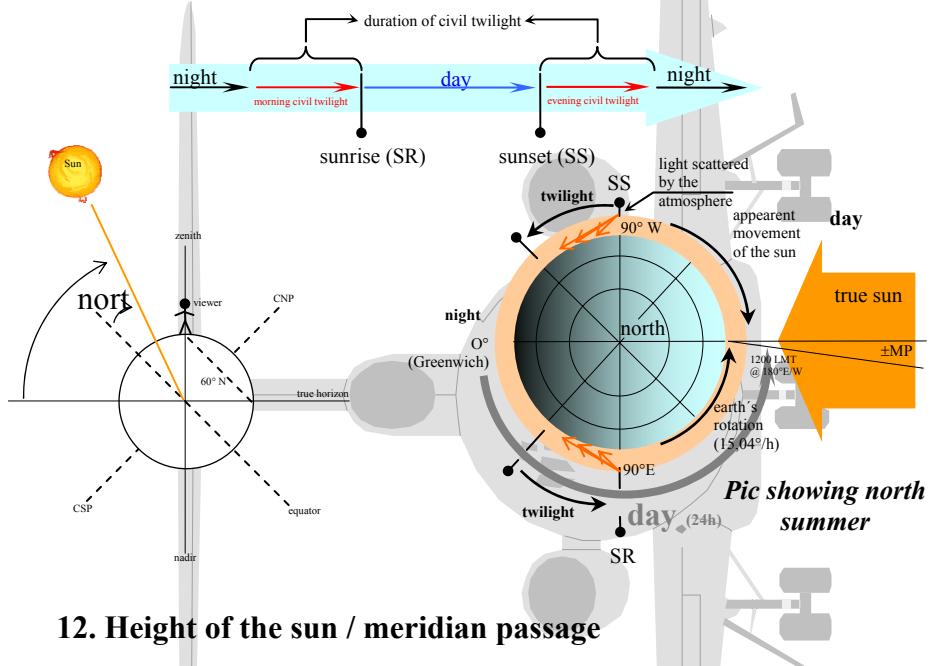


Notes & Drafts:



11. Time definitions

- UTC: universal time coordinated (artificial time)
- ST: standard time (time defined by state borders)
- LMT: local mean time (time defined by the sun)
- UT: LMT @ Greenwich = LMT – east (+ west) longitude ($15,04^{\circ}/\text{h}$)
- DST: daylight saving time (check relevant AIP if applicable)



12. Height of the sun / meridian passage

Height in ${}^{\circ}$ Lat: $h = (90 - \rho) \pm \text{dec}$; (ρ = Lat of viewer position, dec = declination of the sun - see actual air almanac)

- Dec of sun and lat of viewers position in same hemisphere: add dec
- Dec of sun and lat of viewers position in contrary hemisphere: subtract dec
- Equation of time: $LMT \pm MP = \text{true sun}$ (sun in zenith)

data from air almanac 1990:

Date	Declination	MP /min]
01.jan	23,0°S	+ 04
01.feb	17,1°S	+ 14
01.mar	7,6°S	+ 12
01.apr	4,5°N	+ 04
01.mai	15,1°N	- 03
01.jun	22,1°N	- 02

Date	Declination	MP /min]
01.jul	23,1°N	+ 04
01.aug	18,0°N	+ 06
01.sep	8,3°N	+ 00
01.okt	3,2°S	- 10
01.nov	14,4°S	- 16
01.dec	21,8°S	- 11

Notes & Drafts:

13. Useful bearing / interceptions definitions

bearing (european)	formula	american	GPS/FMS
QDM	MH + RB	magnetic bearing to	BRG
QDR	QDM ± 180°	magnetic bearing from	BRG FROM
QUI	QDM ± Var	true bearing to	
QTE	QDR ± Var	true bearing from	
desired QDM	see interceptions	desired track	DTK
intercept heading	see interceptions	course to steer	CTS

interception	direction	enroute intercept angle (I \angle)	correct to	CTS
inbound	BRG > DTK → right / plus	BRG-DTK + 30° (max 90°)	DTK	DTK + I \angle
	BRG < DTK → left / minus	DTK-BRG + 30° (max 90°)	DTK	DTK - I \angle
outbound	BRG _{from} > DTK _{from} → left / minus	30 / 60 / max 90°	DTK _{FROM}	DTK - I \angle
	BRG _{from} < DTK _{from} → right / plus	30 / 60 / max 90°	DTK _{FROM}	DTK + I \angle

14. Frequencies / modulations / range / disturbances

Range	Freq. [Hz]	Systems
LF	30k.....300k	ADF
MF	300k.....3000k	ADF
HF	3M.....30M	HF COM
VHF	30M.....300M	COM/VOR
UHF	300M.....3000M	GS/Tx/DME/RADAR/GPS
SHF	3G.....30G	PAR/ASDE

Modulation (AM)	
A ₀	CW
A ₁	CW, broken
A ₂	CW + tone
A ₃	voice
A ₉	tone + voice

- Wave length: $\lambda = c/f$
- theoretical range of VHF and higher frequencies (optical range):

$$\text{range} = 1,23 \cdot \sqrt{(\text{height [ft]})} \quad [\text{nm}]$$

(This formula takes the curvature of the earth into account only. Practically, the range is in most cases limited by the transmitter's power and/or by obstacles/mountains)

- Freq's in the LF/MF/HF range can be disturbed by:
 - Statics (convective weather, high solar activity in high latitudes), air density differences (shoreline effect), reflection (mountain effect), interference (fading, twilight effect)



Notes & Drafts:

15. Gyros / AHRS / INS corrections

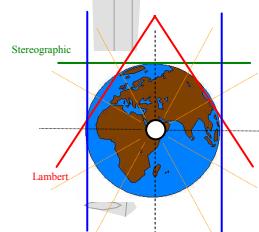
- precession leads initial movement by 90°
- True precession: see system's manual
- Apparent precession:
 - Earth rate precession (ERP)
 - Earth transport precession (ETP)

precession	correction		
	geographic east	geographic north	vector to center of the earth
ERP	none	$\omega_E \cdot \cos \rho$	$\omega_E \cdot \sin \rho$
ETP	v_N/R	v_E/R	$(v_N/R) \cdot \tan \rho$

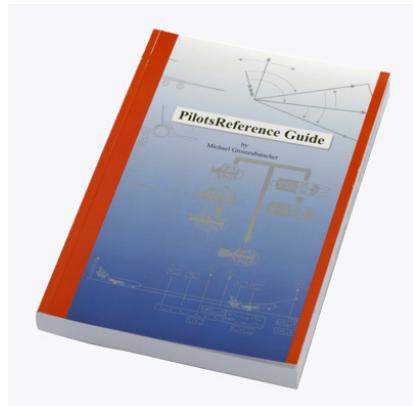
- v_N : a/c speed vector northbound
- v_E : a/c speed vector eastbound
- R : earth's radius plus inflight height
- ρ : geo. latitude
- ω_E : earth's rotation ($15,04^\circ/h$)

16. Chart projections

projection	projection center	chart's straight line	used for lat: (N/S)
stereographic	earth's center, adj. pole	stereodrome	50°...90°, Wx charts
Lambert	earth's center	lambodrome ≈ great circle	20°...70°
Mercator	earth's center	rhumb line	0°...40°



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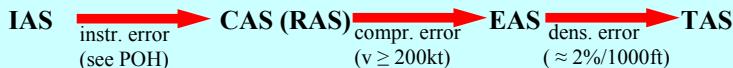
II. Performance

1. General

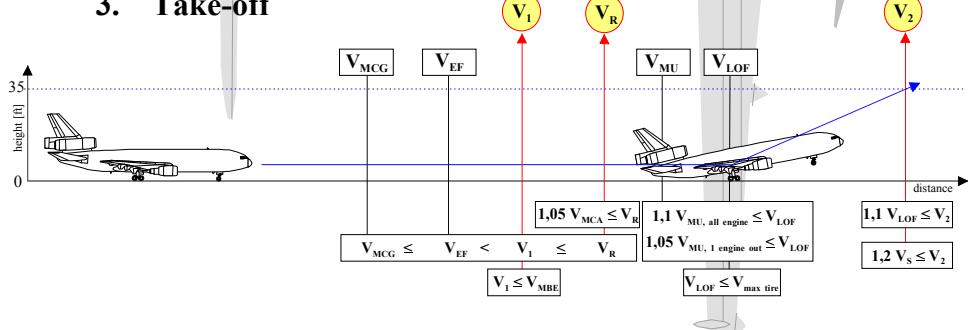
- Maximum altitude:
 - Aerodynamic ceiling:
 - Service ceiling:
 - Max operating alt:
 - Absolute alt:
 - max. alt. for 30° bank in level flight
 - convergence of high and low speed buffet
 - $ROC_{\text{all engines}} = 100 \text{ ft/min}$, $ROC_{\text{SE}} = 50 \text{ ft/min}$
 - max cabin alt (FL80) + Δp_{\max}
 - rate of climb (ROC) = 0 ft/min
- $SR = \frac{NAM}{m_{\text{fuel}}} = \frac{TAS}{FF} ; SC = \frac{1}{SR}$
- $ROC [\text{ft/min}] = GS[\text{kt}] \cdot \text{Climb Gradient [\%]} \cdot 1,013$
- $\text{Climb Gradient [ft/nm]} = \text{Climb Gradient [\%]} \cdot 60,75$

$$ROC = \frac{\text{Thrust} - \text{Drag}}{\text{mass}} \cdot TAS; \text{Climb Gradient [\%]} = \frac{\text{Excess Thrust}}{\text{mass}} \cdot 100$$

2. Speeds



3. Take-off

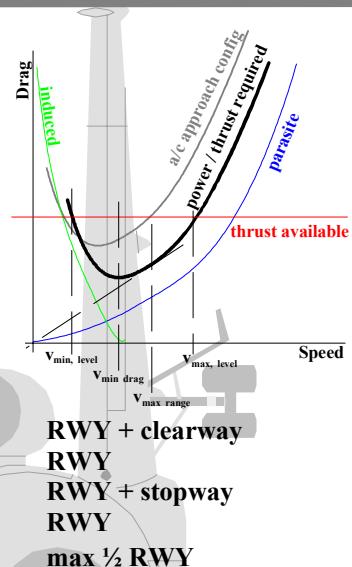


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- Take off distance , Drag curve

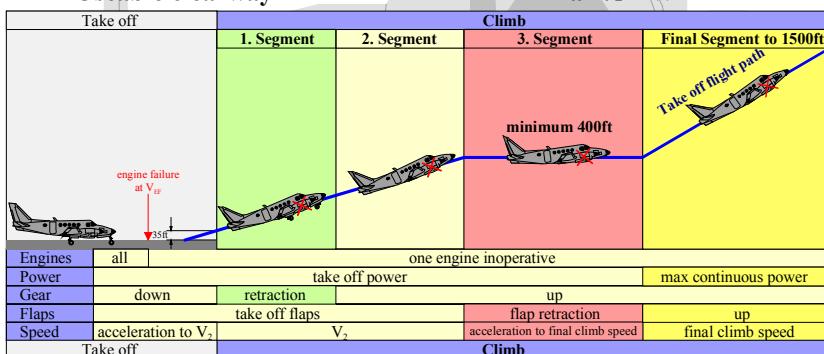
TOD/TOM:
all engines
single engine
abort case
MTOM

lowest mass or longest distance

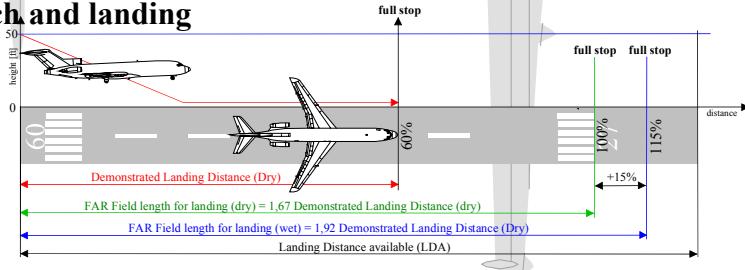


- Take Off Field definitions

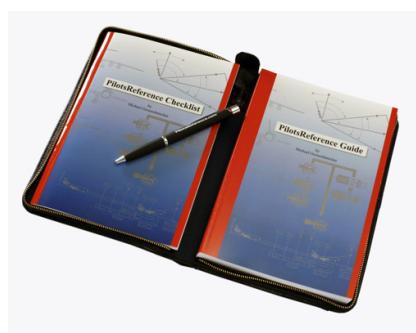
- TODA
- TORA
- ASDA
- LDA
- Usable clearway



4. Approach and landing



Notes & Drafts:

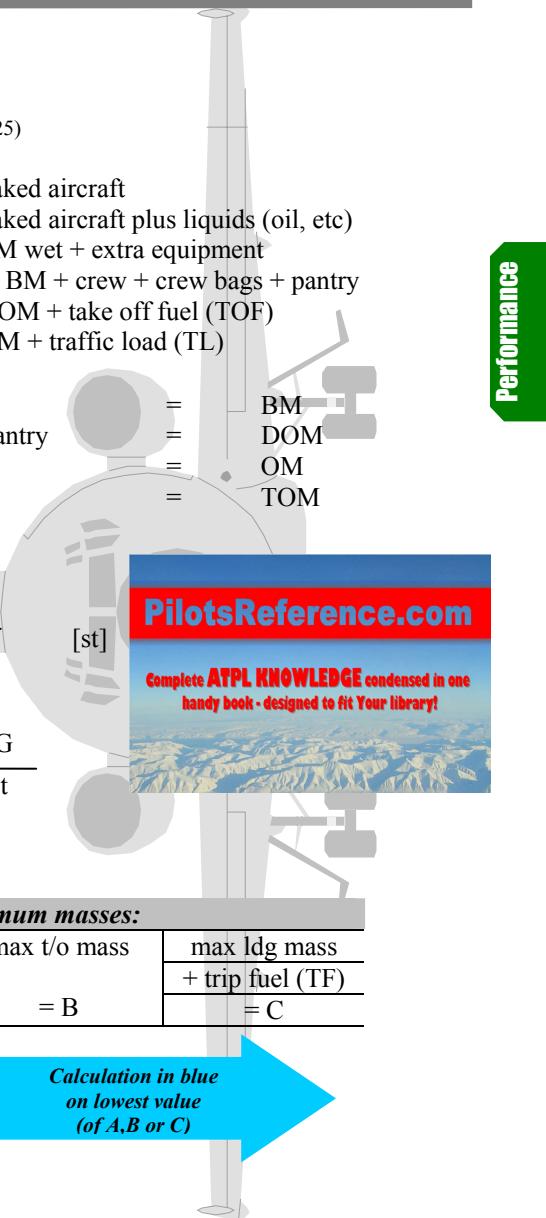


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III. Weight & Balance

1. Definitions (JAR-OPS 1.605...1.625)

- Empty mass (EM): naked aircraft
 - Empty mass wet (EM wet): naked aircraft plus liquids (oil, etc)
 - Basic mass (BM): EM wet + extra equipment
 - Dry operating mass (DOM): BM + crew + crew bags + pantry
 - Operating mass (OM): DOM + take off fuel (TOF)
 - Take off mass (TOM): OM + traffic load (TL)
- ⇒ EM wet + equip.
BM + crew + crew bags + pantry
DOM + TOF
OM + TL



2. Center of gravity (CG)

$$CG = \frac{\sum_i(m_i \cdot st_i)}{m_{total}}$$

3. Shift equation

$$\frac{m_{shift}}{m_{total}} = \frac{\Delta CG}{\Delta st}$$

4. Lowest of A/B/C method

Actual:	Maximum masses:		
DOM	max zero fuel mass	max t/o mass	max ldg mass
+TOF	+ TOF		+ trip fuel (TF)
= OM	= A (lowest)	= B	= C
- OM			
= allowable TL			
- act. TL			
= underload			

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IV. Flight Planning

1. Nautical air miles (NAM)

- WCA/GS calculation \rightarrow time_{leg}
- $NAM_{leg} = TAS_{leg} \cdot time_{leg}$ = still air distance range

2. Overhead/overhead flight planning

$$\sum_{leg} NAM_{leg} + add_{climb} + add_{enroute climb} - sub_{descent} = TF$$

3. VFR reserves

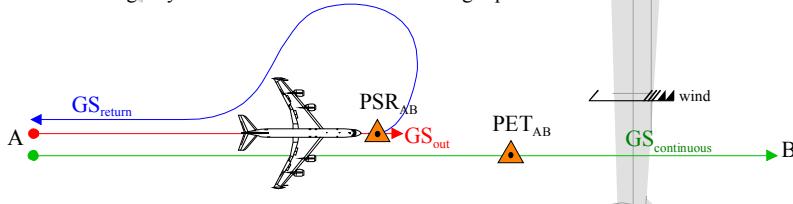
FAA: VFR day \rightarrow 30 minutes res. ; VFR night \rightarrow 45 minutes res.

4. IFR reserves

Rules to apply	Trip (TF) plus \rightarrow	Reserve (+ fuel for all predictable delays)		
		Contingency	Alternate	Holding
EUOPS piston	Cruise power set	5% of TF	Opt. Power	45 min
EUOPS turbine	Cruise power set	5% of TF	Opt. Power	30 min
FAA	Cruise power set	None	Opt. Power	45 min

5. Long range (reclearance procedure)

- Point of safe return: $PSR_{ab-x} = \frac{GS_{return}}{GS_{return} + GS_{out}}$ · Endurance_{rest} [time]
- Point of equal time: $PET_{ab-x} = \frac{GS_{return}}{GS_{return} + GS_{continuous}}$ · Dist_{ab} [dist.]
- First decision point: $FDP = \frac{\text{shortfall}}{\text{contingency}}$ · FT [time]
- If contingency > shortfall \Rightarrow flight possible



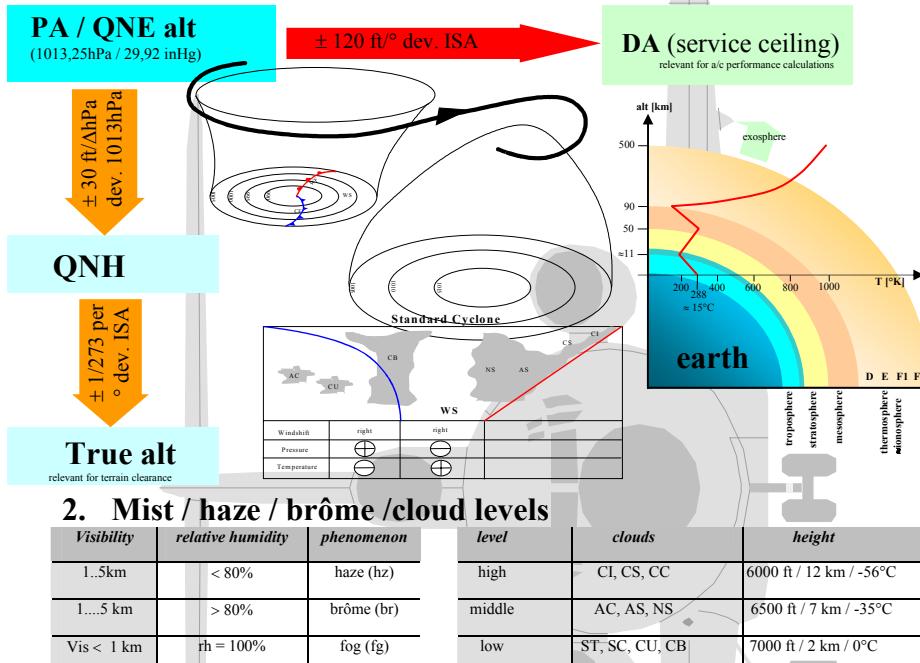
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V. Meteorology

1. General

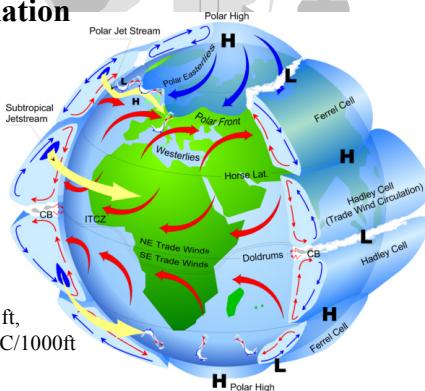


2. Mist / haze / brôme / cloud levels

Visibility	relative humidity	phenomenon	level	clouds	height
1...5km	< 80%	haze (hz)	high	CI, CS, CC	6000 ft / 12 km / -56°C
1....5 km	> 80%	brôme (br)	middle	AC, AS, NS	6500 ft / 7 km / -35°C
Vis < 1 km	rh = 100%	fog (fg)	low	ST, SC, CU, CB	7000 ft / 2 km / 0°C

3. Topographic / global circulation

pressure	flight level	analysis
850 hPa	50	temperature
700 hPa	100	humidity
500 hPa	180	wind
300 hPa	300	jet



4. ISA / adiabatic gradients

- ISA sea level: 15°C , 1013,25hPa
- ISA lapse rate: $-2^{\circ}\text{C}/1000 \text{ ft}$
- relative humidity: 0% (ISA)
- adiabatic lapse rate: dry $\approx -3^{\circ}\text{C}/1000 \text{ ft}$, Saturated $\approx 1..2^{\circ}\text{C}/1000\text{ft}$

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VI. Aerodynamics

(β = bank angle, n = load factor, $g = 9,81 \text{ ms}^{-2}$)

1. Formulas

- Standard turn: $\beta = \frac{\text{TAS}}{10}$ [°]
- Load factor: $n = \frac{1}{\cos \beta}$ [1]
- Stall speed increase: $v_{s,n>1} = v_s \cdot \sqrt{n}$ [kt]
- Radius of turn: $R_{\text{turn}} = \frac{v^2}{g \cdot \tan \beta}$ [m]
- Rate of rotation (metric input!) $RR = \frac{\tan \beta}{2 \cdot \pi \cdot v} \cdot 360 \cdot g$ [$^{\circ}\text{s}^{-1}$]
- Slipping turn: inclinometer ball outbound / descent tendency
- Skidding turn: inclinometer ball inbound / climb tendency
- Level off radius (metric input!) $R_{\text{level off}} = \frac{v^2}{g \cdot (n-1)}$ [m]
- Stall speed with flaps $v_{s0} = v_s \cdot \sqrt{\left(\frac{c_{L,\max, \text{clean}}}{c_{L,\max, \text{flaps}}}\right)}$ [kt]
- Sonic speed $M = \frac{\text{TAS}}{\alpha}$ [1]; $\alpha = 39 \cdot \sqrt{T}$ [kt]; (T in $^{\circ}\text{K}$!)
- SAT/TAT conversion $SAT = TAT - \frac{IAS}{10}$ (appr. 200 kt < IAS)

2. Lift / Drag

$$L = c_L \cdot A \cdot \frac{1}{2} v^2 \cdot \rho ; D = c_D \cdot A \cdot \frac{1}{2} v^2 \cdot \rho$$

3. Limit loads (JAA/FAA part 25, SF = 1,5)

- Clean: limit +2,5 / -1,0; ultimate +3,75 / -1,5 [g]
- Flaps: limit +2,0 / -0,0; ultimate +3,00 / -0,0 [g]

4. v/n diagram vertical gust speed conversion:

- $v_B = \pm 66 \text{ ft} \cdot \text{s}^{-1} = \pm 20 \text{ m} \cdot \text{s}^{-1} = \pm 4000 \text{ ft} \cdot \text{min}^{-1}$
- $v_C = \pm 50 \text{ ft} \cdot \text{s}^{-1} = \pm 15 \text{ m} \cdot \text{s}^{-1} = \pm 3000 \text{ ft} \cdot \text{min}^{-1}$
- $v_D = \pm 25 \text{ ft} \cdot \text{s}^{-1} = \pm 7,6 \text{ m} \cdot \text{s}^{-1} = \pm 1500 \text{ ft} \cdot \text{min}^{-1}$

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VII. Hypoxia / Supplemental Oxygen

1. Hypoxia

<i>breathing</i>	<i>first deficiencies</i>	<i>death</i>
air	10000 ft	22000 ft
100% oxygen	38000 ft	43000 ft
pressure (O_2)	45000 ft	50000 ft

2. Time of useful consciousness (TUC)

<i>Altitude</i>	<i>TUC</i>
25000 ft	5 min
27000 ft	3 min
30000 ft	90 sec

<i>Altitude</i>	<i>TUC</i>
35000 ft	45 sec
40000 ft	20 sec
43000 ft	15 sec

3. Oxygen requirements (FAA/EUOPS check EUOPS 1.385, 1.770...1.775)

EUOPS	
<i>Cabin</i>	<i>oxygen for</i>
Unpressurized	All occupants above F100
Pressurized	All until descent to F100 made

FAA: part 91 (cabin pressures)	
<i>above</i>	<i>oxygen for</i>
12500 ft MSL	for min. Crew (after 30 min)
14000 ft MSL	for min. Crew, always
15000 ft MSL	for each occupant, always

EUOPS: each commander shall ensure that:	
<i>above</i>	<i>oxygen for</i>
13000 ft	All flight crew req. for safe flight
10000 ft	as above if longer than 30 min

FAA: pressurized cabin a/c (part 91)	
<i>above</i>	<i>oxygen for</i>
FL 250	10 min. + emerg. oxygen
FL 350 single hand	mask on, auto sup. if ep>14000 ft
FL 350 multicrew	masks off, if quick donning avail.
FL 410	One CM mask on

quick donning masks shall be available in a/c certified for flights above FL 250

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VIII. Further Regulations

1. IFR planning minima (JAA, commercial only)

Airport	predicted weather at ETA $\pm 1h$	
T/O alternate	sufficient for intended type of approach	
destination	sufficient for intended type of approach	
enroute / dest. alt	intended approach CAT II / III CAT I non precision approach circling approach	pred. Wx sufficient for CAT I non precision approach non prec. + 200ft/1000m circling approach

2. Life vests (private/commercial: check EUOPS 1.825)

- 50nm over water and/or APP/DEP over water
- SE a/c additionally when out of glide distance to reach land

3. Dinghies (commercial: check EUOPS 1.830)

- 400nm over water or 120min whichever is less (check ETOPS if applicable)

